

# OptBinning: The Python optimal binning library

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## The OptBinning library

# Types of binning algorithms

- ▶ Unsupervised binning techniques
  - ▶ Equal-width interval binning
  - ▶ Equal-size or equal-frequency interval binning
- ▶ Supervised binning techniques
  - ▶ Merging: Monotone Adjacent Pooling Algorithm
  - ▶ Decision trees: CART, Minimum Description Length Principle (MDLP), condition inference trees (CTREE)
- ▶ Fast and robust algorithms ✓
- ▶ Constraints ✗

## Mathematical optimization framework (1/4)

Definition: The optimal binning is the optimal discretization of a variable into bins given a discrete or continuous numeric target.

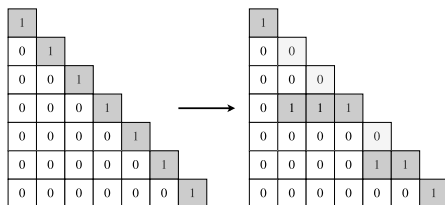
- ▶ Pre-binning
  - ▶  $m$  split points,  $s_1 < s_2 < \dots < s_m$  to create  $n = m + 1$  pre-bins. These pre-bins are defined by the intervals  $(-\infty, s_1), [s_1, s_2), \dots, [s_m, \infty)$ .
- ▶ Optimization
  - ▶ Decision variable:  $X_{ij} \in \{0, 1\}, \forall (i, j) \in \{1, \dots, n : i \geq j\}$ .

- ▶ Each column must contain exactly one 1. For  $j = 1, \dots, n$

$$\sum_{i=1}^n X_{ij} = 1.$$

- ▶ Continuity by rows, no 0 – 1 gaps are allowed. For  $i = 1, \dots, n; j = 1, \dots, i - 1$

$$X_{ij} \leq X_{ij+1}.$$



## Mathematical optimization framework (2/4)

Objective function with binary and multi-class target, maximize a divergence measure (Jeffrey's divergence). Given non-event ( $y = 0$ ) and event ( $y = 1$ )

$$J(P||Q) = IV = \sum_{i=1}^n (p_i - q_i) \log \left( \frac{p_i}{q_i} \right), \quad p_i = \frac{r_i^{NE}}{r_T^{NE}}, \quad q_i = \frac{r_i^E}{r_T^E}.$$

$$V_{ij} = \left( \sum_{z=j}^i \frac{r_z^{NE}}{r_T^{NE}} - \frac{r_z^E}{r_T^E} \right) \log \left( \frac{\sum_{z=j}^i r_z^{NE} / r_T^{NE}}{\sum_{z=j}^i r_z^E / r_T^E} \right), \quad i = 1, \dots, n; j = 1, \dots, i.$$

The IV can be computed using the described parameters and the decision variables  $X_{ij}$ , yielding

$$IV = \sum_{i=1}^n \left( \sum_{j=1}^i \left( \frac{r_j^{NE}}{r_T^{NE}} - \frac{r_j^E}{r_T^E} \right) X_{ij} \right) \log \left( \frac{\sum_{j=1}^i r_j^{NE} / r_T^{NE} X_{ij}}{\sum_{j=1}^i r_j^E / r_T^E X_{ij}} \right).$$

## Mathematical optimization framework (3/4)

Pre-compute all possible merges in linear-time

- ▶ Transform non-convex MINLP to IP
- ▶ Linearize objective function (exploit continuity constraint)

Optimal  $V_{ij}$  ( $V_i$ ) by row,  $i = 1, \dots, n$ :

$$V_i = V_{i1}X_{i1} + \sum_{j=2}^i V_{ij}(X_{ij} - X_{ij-1}) \iff V_{ii}X_{ii} + \sum_{j=1}^{i-1} (V_{ij} - V_{ij+1})X_{ij}.$$

Objective function:

$$\sum_{i=1}^n V_{ii}X_{ii} + \sum_{j=1}^{i-1} (V_{ij} - V_{ij+1})X_{ij}.$$

## Mathematical optimization framework (4/4)

Basic MIP formulation:

$$\max_X \quad \sum_{i=1}^n V_{ii} X_{ii} + \sum_{j=1}^{i-1} (V_{ij} - V_{ij+1}) X_{ij} \quad (1a)$$

$$\text{s.t.} \quad \sum_{i=j}^n X_{ij} = 1, \quad j = 1, \dots, n \quad (1b)$$

$$X_{ij} - X_{ij+1} \leq 0, \quad i = 1, \dots, n; j = 1, \dots, i-1 \quad (1c)$$

$$b_{\min} \leq \sum_{i=1}^n X_{ii} \leq b_{\max} \quad (1d)$$

$$r_{\min} X_{ii} \leq \sum_{j=1}^i r_j X_{ij} \leq r_{\max} X_{ii}, \quad i = 1, \dots, n \quad (1e)$$

$$r_{\min}^{NE} X_{ii} \leq \sum_{j=1}^i r_j^{NE} X_{ij} \leq r_{\max}^{NE} X_{ii}, \quad i = 1, \dots, n \quad (1f)$$

$$r_{\min}^E X_{ii} \leq \sum_{j=1}^i r_j^E X_{ij} \leq r_{\max}^E X_{ii}, \quad i = 1, \dots, n \quad (1g)$$

$$X_{ij} \in \{0, 1\}, \quad \forall (i, j) \in \{1, \dots, n : i \geq j\} \quad (1h)$$

## Constraints: monotonicity (1/3)

Impose monotonic trends between consecutive bins

- ▶ 6 modes: Ascending/descending, peak/valley, convex/concave
- ▶ 2 auto modes: auto and auto ascending/descending

Auto modes: Auto monotonic trend using Machine Learning algorithm to determine the trend maximizing divergence.

Integer and constraint programming formulation techniques:

- ▶ Disjoint constraints
- ▶ Big-M constraints
- ▶ Half-reified linear constraints



## Constraints: monotonicity (2/3)

For  $i = 1, \dots, n$ ;  $j = 1, \dots, i$

$$D_{ij} = \frac{\sum_{z=j}^i r_z^E}{\sum_{z=j}^i r_z}$$

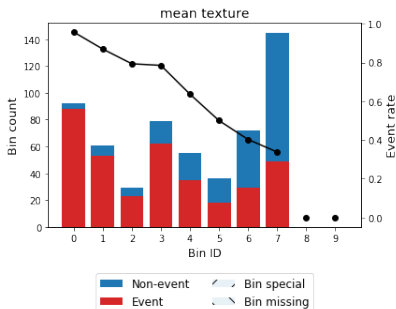
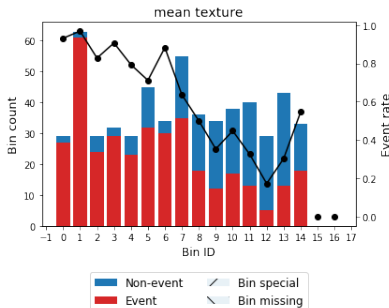
For  $i = 1, \dots, n$ .

$$D_{i.} = D_{ii}X_{ii} + \sum_{j=1}^{i-1} (D_{ij} - D_{ij+1})X_{ij}.$$

For  $i = 2, \dots, n$ ;  $z = 1, \dots, i - 1$

$$D_{ii}X_{ii} + \sum_{j=1}^{i-1} (D_{ij} - D_{ij+1})X_{ij} + \beta(X_{ii} + X_{zz} - 1)$$

$$\leq 1 + (D_{zz} - 1)X_{zz} + \sum_{j=1}^{z-1} (D_{zj} - D_{zj+1})X_{zj}.$$



## Constraints: monotonicity (3/3)

The peak and valley trend define an event rate function exhibiting a single trend change or reversal.

$$i - n(1 - y_i) \leq t \leq i + ny_i, \quad i = 1, \dots, n \quad (2a)$$

$$t \in [0, n] \quad (2b)$$

$$y_i \in \{0, 1\}, \quad i = 1, \dots, n \quad (2c)$$

Peak trend constraints

$$\begin{aligned} & y_i + y_z + 1 + (D_{zz} - 1)X_{zz} + \sum_{j=1}^{z-1} (D_{zj} - D_{zj+1})X_{zj} \\ & \geq D_{ii}X_{ii} + \sum_{j=1}^{i-1} (D_{ij} - D_{ij+1})X_{ij}, \quad i = 2, \dots, n; \quad z = 1, \dots, i - 1, \\ & 2 - y_i - y_z + 1 + (D_{ii} - 1)X_{ii} + \sum_{j=1}^{i-1} (D_{ij} - D_{ij+1})X_{ij} \\ & \geq D_{zz}X_{zz} + \sum_{j=1}^{z-1} (D_{zj} - D_{zj+1})X_{zj}, \quad i = 2, \dots, n; \quad z = 1, \dots, i - 1. \end{aligned}$$

## Constraints: Reduction of dominant bins

To prevent any particular bin from dominating the results and producing more homogeneous solutions.

$$\max_{X, \rho_{\min}, \rho_{\max}} \sum_{i=1}^n V_{ii} X_{ii} + \sum_{j=1}^{i-1} (V_{ij} - V_{ij+1}) X_{ij} - \gamma(\rho_{\max} - \rho_{\min})$$

s.t. (1b - 1h)

$$\rho_{\min} \leq r_T(1 - X_{ii}) + \sum_{j=1}^i r_j X_{ij}, \quad i = 1, \dots, n$$

$$\rho_{\max} \geq \sum_{j=1}^i r_j X_{ij}, \quad i = 1, \dots, n$$

$$\rho_{\min} \leq \rho_{\max}$$

$$\rho_{\min} \geq 0.$$

$$\rho_{\max} \geq 0.$$

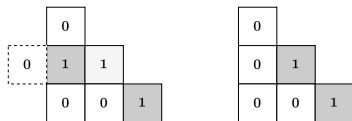
## Constraints: Maximum p-value

A necessary constraint to guarantee that event rates between consecutive bins are statistically different.

- ▶ Binary target: Z-test for proportions
- ▶ Continuous target: T-test

Use preprocessing procedure to detect pairs of pre-bins that do not satisfy the p-value constraints. Two cases are considered depending on  $j$ :

$$\begin{cases} X_{ij} + X_{kl} \leq 1 + X_{kl-1} & \text{if } j = 1, \\ X_{ij} + X_{kl} \leq 1 + X_{ij-1} + X_{kl-1} & \text{if } j > 1 \end{cases}, \quad \forall (i, j, k, l) \in \mathcal{I}.$$

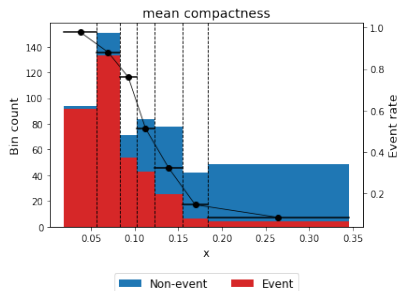


**Figure:** General violation constraint between two feasible solutions. Case  $j = 1$  (left). Case  $j > 1$  (right).

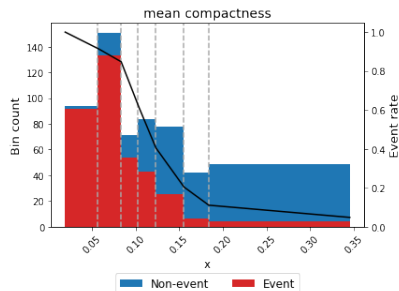
# Optimal piecewise binning

- ▶ Classical binning algorithms: discontinuous piecewise constant function
- ▶ Constant value reduces the granularity of the transformation
- ▶ Discontinuities are a source of unfairness
- ▶ Good compromise between accuracy and explainability

## Discontinuous piecewise constant



## Continuous piecewise linear



## Optimal piecewise binning: MIP formulation

Pre-binning produces mutually exclusive sets of indices satisfying

$$n = \sum_{j=1}^B |\mathcal{I}_j|$$

Basic MINLP formulation:

- ▶ Binary case  $y = P[Y = 1|X = x]$  using ML estimator
- ▶ Polynomial degree  $K$

$$\min \sum_{j=1}^B \left( \sum_{i \in \mathcal{I}_j} \left| y_i - \sum_{k=1}^K c_{jk} x_i^{k-1} \right|^p \right)^{1/p} \quad (5a)$$

$$\text{s.t.} \quad \sum_{k=1}^K c_{jk} s_j^{k-1} = \sum_{k=1}^K c_{j+1k} s_j^{k-1}, \quad j = 1, \dots, B-1 \quad (5b)$$

$$l_j \leq \sum_{k=1}^K c_{jk} x_i^{k-1} \leq u_j, \quad j = 1, \dots, B, i \in \mathcal{I}_j \quad (5c)$$

$$c_{jk} \in \mathbb{R}, \quad j = 1, \dots, B, k = 1, \dots, K \quad (5d)$$

Objective with  $p = \{1, 2\}$  and suitable for quantile regression.

## Optimal piecewise binning: additional constraints

Ascending/descending monotonicity

$$\sum_{k=1}^K c_{jk}(k-1)x_j^{k-2} \geq 0, \quad j = 1, \dots, B, \quad i \in \mathcal{I}_j$$

$$\sum_{k=1}^K c_{jk}(k-1)x_j^{k-2} \leq 0, \quad j = 1, \dots, B, \quad i \in \mathcal{I}_j$$

Regularization: avoid coefficients for large  $K$  when unnecessary.

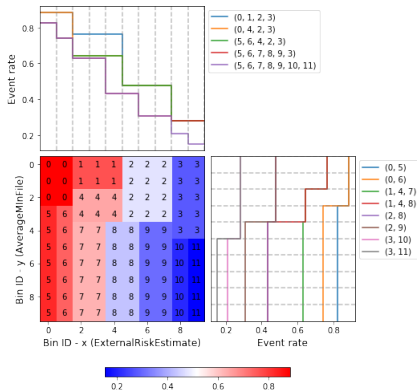
$$\min \sum_{j=1}^B \left( \sum_{i \in \mathcal{I}_j} \left| y_i - \sum_{k=1}^K c_{jk} x_i^{k-1} \right|^p \right)^{1/p} + \|c\|_{p'}$$

Implementation using SOCP solver in the RoPWR library [NP20c].

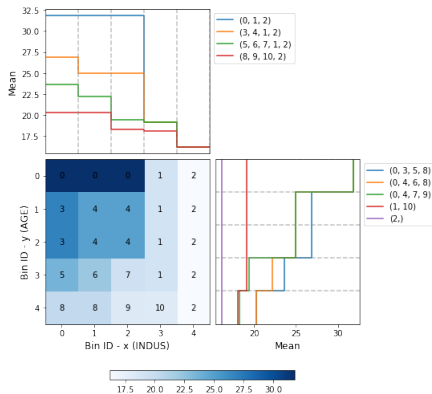
# Optimal Binning 2D

Extension to 2D binning (two features  $x_1$ ,  $x_2$  and target  $y$ ). Many of the 1D binning constraints are applicable, including monotonicity planes.

## Binary target



## Continuous target





# The OptBinning library

- ▶ Python library, open source (Apache-2.0)
  - ▶ 15,231 cloc (v0.17.2) + 3,205 cloc (173 unit tests)
- ▶ GitHub: <https://github.com/guillermo-navas-palencia/optbinning>
  - ▶ Current version: 0.17.2
  - ▶ GitHub stars: 301
  - ▶ Downloads: > 5.3M (~90k/month)
- ▶ Documentation: <http://gnpalencia.org/optbinning/>
- ▶ Dependencies
  - ▶ Data: NumPy, Pandas
  - ▶ Stats: SciPy, scikit-learn, RoPWR
  - ▶ Optimization: Google OR-Tools / LocalSolver (optional - commercial)
  - ▶ Plots: Matplotlib
- ▶ Functionalities
  - ▶ Optimal binning for binary, continuous and multi-class target [NP20b]
  - ▶ Optimal binning over data streams [NP20a]
  - ▶ Optimal binning with uncertainty
  - ▶ Scorecard development
  - ▶ Counterfactual explanations for scorecard models [NP21]

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Gracias!